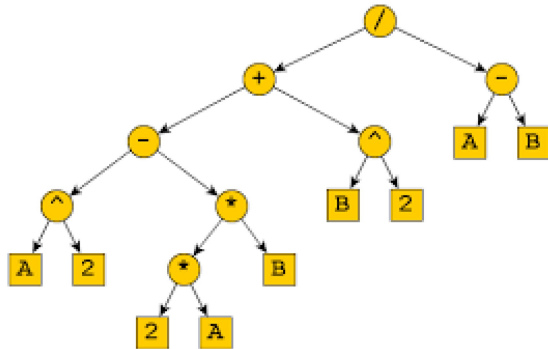


## Lecture 29 Rooted Trees

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Grimaldi 12.2



Assignment #8 due Mon. Dec 7th.  
Worth 3% of your grade.

Final exam

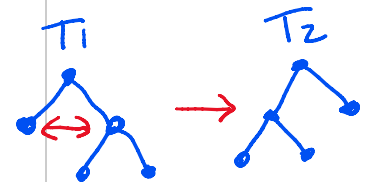
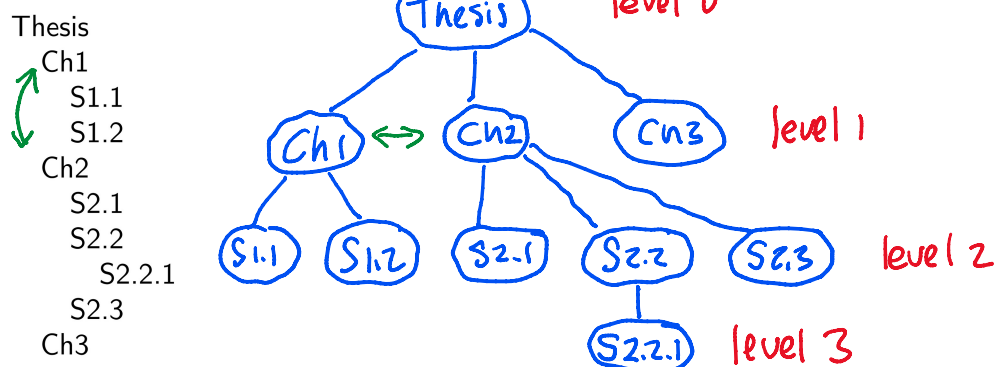
Part I 20% rest.  
Part II 20% A7 and A8

What formula does this tree encode?

## Ordered rooted trees

For some applications it is essential to have not just a rooted tree, but also an ordering of the children for each internal vertex.

Example



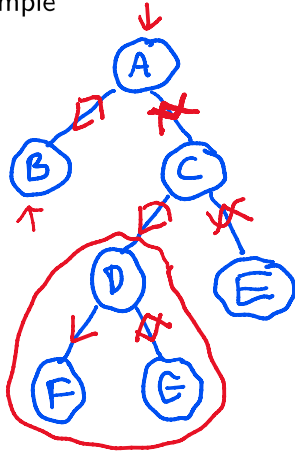
How do we walk through and process a rooted tree?

### Definition ( preorder, postorder tree traversals )

A **preorder traversal** of a tree  $T$  first visits the root vertex then visits, in preorder, the vertices of the subtrees  $T_1, T_2, \dots, T_k$  of  $T$ .

A **postorder traversal** of a tree  $T$  visits, in postorder, the vertices of the subtrees  $T_1, T_2, \dots, T_k$  of  $T$  then visits the root.

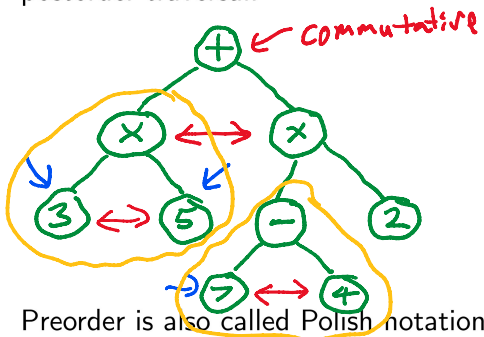
Example



preorder:  $A B C (D F G) E$   
 postorder:  $B (F G D) E C \underline{A}$

Exercise. Draw the expression tree for  $(3 \times 5) + ((7 - 4) \times 2)$  and give the postorder traversal.

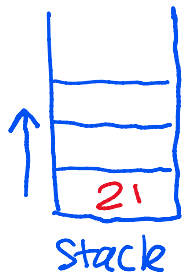
$$\begin{array}{c} \downarrow \quad \downarrow \\ (3 \times 5) + ((7 - 4) \times 2) \\ 15 + 3 \times 2 = 21. \end{array}$$



postorder:  $(3 \ 5 \times) (7 \ 4 \ -) 2 \times +$

Preorder is also called Polish notation and postorder is also called reverse Polish notation. HP calculators used postorder and a stack to evaluate expressions.

Don't need brackets!



Rules:

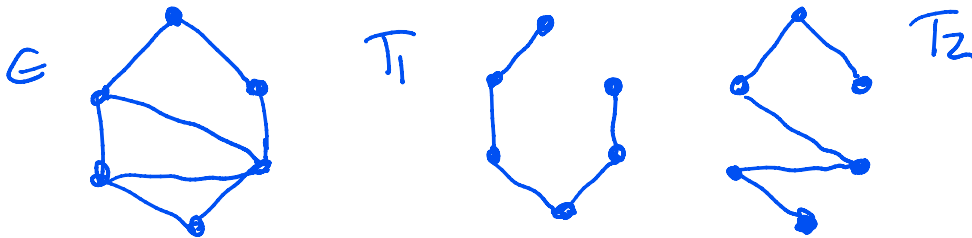
Number? Put it on the top of the stack.  
 Operator? Take the top 2 items off the stack, operate, and put the result on the top of the stack.

$3 \ 5 \times \ 7 \ 4 \ - \ 2 \times \ +$   
 $\uparrow \ \uparrow \ \uparrow \ \uparrow \ \uparrow \ \uparrow \ \uparrow \ \uparrow$

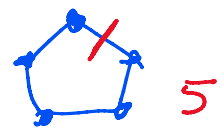
## Definition (spanning tree)

Let  $G$  be a connected multigraph. A subgraph  $T$  of  $G$  is a **spanning tree** if  $T$  spans  $G$  (so  $T$  contains all vertices in  $G$ ) and  $T$  is a tree.

Example



How many spanning trees does a cycle have?



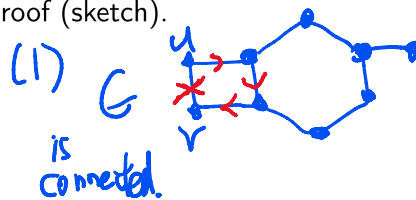
## Theorem (existence of spanning trees)

Every connected multigraph  $G = (V, E)$  has a spanning tree.

Here are two algorithms to select a spanning tree in  $G$ :

- (1) Start from  $G$ . If there is a cycle  $C$  in  $G$  delete an edge from  $C$ . Repeat this until  $G$  has no cycles. Output  $G$ .
- (2) Create the graph  $H = (V, \phi)$ . For each edge  $e$  in  $G$  add  $e$  to  $H$  if it does not make  $H$  have a cycle. Output  $H$ .

Proof (sketch).



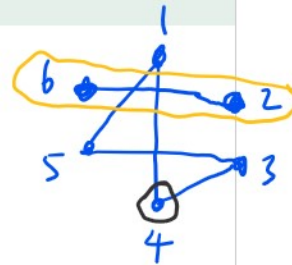
Deleting an edge on a cycle in  $G$  preserves connectivity.

End up with a connected graph with no cycles. A tree by def. with all the vertices.

(2) Exercise.

# Graph Algorithms

Consider the graph  $G = (V, E)$  where  $V = \{1, 2, 3, 4, 5, 6\}$  and  $E = \{\{1, 5\}, \{5, 3\}, \{4, 1\}, \{4, 3\}, \{2, 6\}\}$ .



How can a computer test if  $G$  is connected? planar?

If  $G$  is connected, how can it find a spanning tree in  $G$ ?

If  $G$  is planar, how can it find a planar embedding of  $G$ ?

Most algorithms need to visit the **neighbors** of a vertex.

**Question:** What is a good way to store the edges?

## Definition ( list of neighbors )

The **list of neighbors** representation for  $E$  is an array  $A$  of size  $n = |V|$  where  $A_i$  is the set of neighbors of vertex  $i$  (the vertices adjacent to  $i$ ).

Example

|     | 1          | 2       | 3          | 4          | 5          | 6       |
|-----|------------|---------|------------|------------|------------|---------|
| $A$ | $\{4, 5\}$ | $\{6\}$ | $\{4, 5\}$ | $\{1, 3\}$ | $\{1, 3\}$ | $\{2\}$ |

**Question:** How do algorithms walk through the graph?

## The Depth-First Search (DFS) algorithm

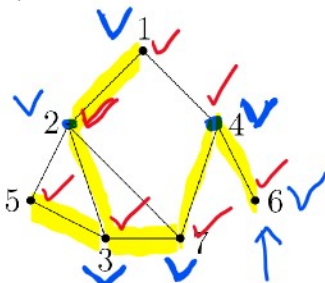
**Input.** A graph  $G = (V, E)$ .

**Output.** A set  $E_T$  of edges such that  $(V, E_T)$  is a spanning tree of  $G$ .

1. **Let**  $v = 1$ ,  $E_T = \emptyset$  and mark vertex 1 as visited.
2. **If** all neighbors of  $v$  have been visited **Then**
  - a) **If**  $v = 1$  **Then Return**  $(V, E_T)$ .
  - b) **Else** (backtrack step) **Let**  $v = \text{parent}(i)$  and **Goto** step 2.
3. **Else**
  - a) **Let**  $i$  be the smallest neighbor of  $v$  that has not been visited.
  - b) Mark  $i$  as visited.
  - c) Add the edge  $\{v, i\}$  to  $E_T$  and **Let**  $\text{parent}(i) = v$ .
  - d) **Let**  $v = i$  and **Goto** step 2.

Modify this DFS algorithm to test if  $G$  is connected, has a cycle.

Example



Depth First Search Spanning Tree.

$E_T = \{ \{1, 2\}, \{2, 3\}, \{3, 5\}, \{3, 7\}, \{4, 7\}, \{4, 6\} \}$

|            | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|------------|---|---|---|---|---|---|---|
| parent     |   | 1 | 2 | 7 | 3 | 4 | 3 |
| mark array |   |   |   |   |   |   |   |

Additional Space